

Graphical Models of Residue Coupling in Protein Families

John Thomas
Dept. of Computer Science
Dartmouth College
Hanover, NH 03755
jthomas@cs.dartmouth.edu

Naren Ramakrishnan
Dept. of Computer Science
Virginia Tech
Blacksburg, VA 24061
naren@cs.vt.edu

Chris Bailey-Kellogg
Dept. of Computer Science
Dartmouth College
Hanover, NH 03755
cbk@cs.dartmouth.edu

ABSTRACT

Identifying residue coupling relationships within a protein family can provide important insights into the family's evolutionary record, and has significant applications in analyzing and optimizing sequence-structure-function relationships. We present the first algorithm to infer an undirected graphical model representing residue coupling in protein families. Such a model, which we call a residue coupling network, serves as a compact description of the joint amino acid distribution, focused on the independences among residues. This stands in contrast to current methods, which manipulate dense representations of co-variation and are focused on assessing dependence, which can conflate direct and indirect relationships. Our probabilistic model provides a sound basis for predictive (will this newly designed protein be folded and functional?), diagnostic (why is this protein not stable or functional?), and abductive reasoning (what if I attempt to graft features of one protein family onto another?). Further, our algorithm can readily incorporate, as priors, hypotheses regarding possible underlying mechanistic/energetic explanations for coupling. The resulting approach constitutes a powerful and discriminatory mechanism to identify residue coupling from protein sequences and structures. Analysis results on the G-protein coupled receptor (GPCR) and PDZ domain families demonstrate the ability of our approach to effectively uncover and exploit models of residue coupling.

Keywords

Residue coupling networks, graphical models, evolutionary co-variation, sequence-structure-function relationships

1. INTRODUCTION

When studying a family of proteins that have evolved to perform a particular function, a major goal of contemporary biological research is to uncover constraints that appear to be acting on the family, with an eye toward understanding the molecular mechanisms imposing the constraints. For

example, amino acid conservation has long been recognized as an important indicator of structural or functional significance [27]. In the 1990s, researchers began generalizing single-position conservation to correlated co-evolution of amino acid pairs, thus revealing cooperativity and coupling constraints (e.g., one early study focused on the HIV-1 envelope protein, with the aim of guiding peptide vaccine design [16]). Such works boosted the discovery of coupled residues, which could previously have been identified only by painstaking *in vitro* approaches such as thermodynamic double mutant analysis [11]. The next step was to summarize information about correlated positions into pathways [15], motifs [1, 20], and structural templates [20] in protein families. Today, projects undertake ambitious large-scale recombination [28] or site-directed and combinatorial mutagenesis studies [23] to identify entire building blocks of proteins important to preserve function.

Knowing which pairs (or sets) of residues are coupled in a protein family aids our understanding of many important processes, e.g., conformational change and protein folding [21, 24], signaling [26], protein-protein interaction, and even protein complex assembly [13]. Since the basis for coupling can be structural and/or functional, information about coupled residues can be used predictively for assessing protein structure [25], fold classification [9], or even to suggest novel sequences for protein engineering [22].

While there are many computational techniques for studying residue coupling [6], all methods begin by defining a metric to quantify the degree to which two residues co-vary. Global methods then determine pairs of coupled residues by observing correlated mutations in the protein family multiple sequence alignment (MSA) as a whole (e.g., [16]). The state-of-the-art in understanding residue coupling is, however, a local method—so-called ‘perturbation-based’ analysis [4] introduced by Lockless and Ranganathan [18]. The basic idea is to subset the MSA according to some condition (e.g., containing a moderately conserved residue type at a particular position) and observe the effect of the perturbation on residue distributions at other positions. If the subsetting operation significantly alters the proportions of amino acids at some other position, it is inferred to be coupled to the perturbed position, according to the evolutionary record. Even though this approach is purely sequence-based, it has been shown to uncover structural networks of residues underlying important allosteric communication pathways in proteins [26].

A key missing ingredient to date is a formal probabilistic model capturing the constraints inferred from residue coupling studies. Such a model would help assess the feasibility and significance of performing inference from coupling data, including determining whether coupling is a persistent feature of a protein family or merely a hallucination. The process of inferring such a model would help make explicit the essential constraints underlying the family (e.g., by identifying a small set of correlations that explain the data nearly as well as the complete set). A model would enable the careful combination of multiple information sources (e.g., by integrating priors from structural and functional studies with correlations derived from sequence analysis). Finally, the model would serve as a compact description of the joint amino acid distribution, and could be used for predictive (will this newly designed protein be folded and functional?), diagnostic (why is this protein not stable or functional?), and abductive reasoning (what if I attempt to graft features of one protein family onto another?).

This paper addresses these needs by formulating and elucidating the natural correspondence between residue coupling (qualifying interdependence among residues) and a probabilistic graphical model (summarizing interrelationships between random variables).

1. We present the *first* algorithm to infer an undirected graphical model, which we call a *residue coupling network*, representing coupling relationships in protein families. We bring in ideas from the extensive literature on probabilistic models [3] to derive networks that are meaningful as indicators of joint variation of sequence positions and that also explain structural features of protein families.
2. Unlike current correlated mutation algorithms that are focused on assessing dependence (which can conflate direct and indirect relationships) we focus on assessing *independence* (which enables modular reasoning about variation). We thus derive more compact descriptions of underlying networks highlighting the most important relationships.
3. We demonstrate how hypotheses regarding possible underlying mechanistic/energetic explanations for coupling can be used as priors for computational model discovery. For instance, if we have reason to believe that coupling in a given family would be only between nearby residues, a representative contact graph can be utilized as a valuable prior, benefiting algorithmic complexity and ensuring biological interpretability of the results.

2. BACKGROUND: CORRELATED MUTATIONS AND RESIDUE COUPLING

We begin by providing some background about correlated mutations and how they are used as indicators of residue coupling. Typically, we are given a multiple sequence alignment (MSA) whose rows are the members of the family and the columns are the aligned residue positions. Thus the MSA can be thought of as a matrix A where the value in row s and column j refers to the j th residue according to

sequence s . We ignore columns with more than 50% gaps ('gapful' columns) and ignore in the calculations below the remaining entries that are gaps.

A coupling constraint quantifies the degree to which two positions in the family co-vary. Given positions i and k , information about amino acid occurrences contained in the i th and k th column vectors of the MSA can be summarized into 20-element vectors of frequencies, or probability distributions $P(i)$ and $P(k)$. Essentially, this allows us to think of residue positions as random variables over a discrete sample space of 20 possibilities (recall that we ignore gaps). Coupling can then be estimated by many information-theoretic and statistical metrics; one example is the (global) *mutual information* between $P(i)$ and $P(k)$, given by:

$$MI(i, k) \equiv \sum_{i=1}^{20} \sum_{k=1}^{20} P(i, k) \log \frac{P(i, k)}{P(i)P(k)}$$

Notice that the mutual information is actually the KL divergence [19] between the distributions $P(i, k)$ and $P(i)P(k)$; it quantifies the margin of error in assuming that the joint distribution $P(i, k)$ is decomposable. $MI(i, k)$ is zero when the underlying distributions are independent and non-zero otherwise. Another way to think of $MI(i, k)$ is as the difference

$$MI(i, k) \equiv H(i) - H(i|k)$$

where $H(i)$ is the entropy of the random variable i and $H(i|k)$ is the entropy of the probability distribution $P(i|k)$. If $MI(i, k) = 0$, then knowing the value of k does not reduce our uncertainty about i . A high score of $MI(i, k)$ is typically used as an indicator of coupling [16].

There are other ways to quantify coupling, e.g., using covariances and correlations; see [6]. In contrast to global methods for assessing coupling, perturbation based methods assess coupling between i and k by first selecting the rows of A that have position i fixed to some residue and observing the effect of this *in silico* perturbation on $P(k)$ (notice the asymmetry in this approach). Once again, we can assess the difference between $P(k)$ (before) and $P(k)$ (after) using a variety of metrics [4], including mutual information.

All metrics suffer from estimation problems under high or low degrees of conservation. For instance, if position i is always alanine and position k is always glutamine, then $MI(i, k)$ would be assigned zero even though we have not observed any variation in either! Similar problems arise with residues that have low frequencies of certain amino acids. It is hence well-recognized that 'correlated mutation algorithms must favor an intermediate level of conservation' [6].

A typical use of a coupling study is to visualize the inferred constraints in order to guide further experiments and gain insights into the sequence-structure-function relationship. For example, couplings have been organized into pathways of allosteric communication through the protein [15]. The discovery of such pathways has recently been reinvigorated with the work of [26] where the authors perform perturbation-based analysis at numerous positions and subsequently 'cluster' the pairs of coupled residues; this procedure has been shown to yield sparse, connected networks in many protein families. Researchers have also used cou-

pling constraints as a basis to infer the contact map, since coupled residues are known to often be spatially proximal. This is still a popular way to validate correlated mutation algorithms (e.g., see [4]). Others compare the constraints to known energetic couplings inferred from double mutant experiments [7].

3. LEARNING GRAPHICAL MODELS OF RESIDUE COUPLING

If coupled residues indeed capture meaningful relationships, then they must afford a probabilistic interpretation. That is our working hypothesis for this paper and helps highlight where all previous work falls short. All previous approaches to inferring networks from data do so by direct incorporation of couplings as dependences and, as is well known, such an approach cannot distinguish direct from transitive dependences. It is also clear that (in)dependence of random variables is a very conditional phenomenon: two random variables may be correlated, become uncorrelated in the presence of new evidence, become correlated again when given further evidence, and so on. This means that we must pay careful attention to conditioning contexts, especially when we employ perturbation-based correlated mutation algorithms.

Our proposed approach is to directly learn a *residue coupling network*, an undirected graphical model $N(\mathcal{V}, \mathcal{E})$ that represents the residue coupling relationships. Such a model encodes probabilistic independence between its vertices according to an interpretation such as:

- *Pairwise*: For every pair (a, b) of non-adjacent nodes, a is conditionally independent of b , given every other node;
- *Local*: A node is conditionally independent of all other nodes, given its immediate neighbors; or
- *Global*: If a set of nodes c separates a from b , then a is conditionally independent of b given c .

In asserting independence between a given pair of random variables (nodes), notice that the *Global* interpretation uses a smaller conditioning context than the *Local*, whose conditioning context is even smaller than the *Pairwise* interpretation. For this reason, if a network satisfies the *Global* property, then it will also satisfy the *Local* property. Similarly, the *Local* property implies the *Pairwise* property. Symbolically, $Global \Rightarrow Local \Rightarrow Pairwise$.

Concomitant with the above independence interpretations, we can equally think of a network as representing a factorization of the joint pdf of the random variables in \mathcal{V} (residues):

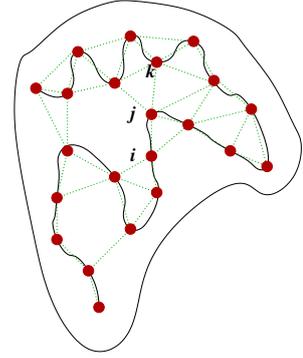
$$P(\{\mathcal{V}\}) = \frac{1}{Z} \prod_{c \in \text{cliques}(N)} \phi_c(v_c) \quad (1)$$

Here, the ϕ_c are potential functions so that

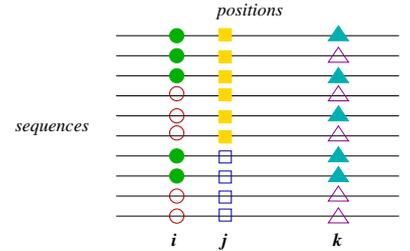
$$Z = \sum_v \prod_{c \in \text{cliques}(N)} \phi_c(v_c) \quad (2)$$

normalizes their product into a probability measure. In Eq. 1 and Eq. 2, v denotes instantiations of the joint sample space of $\{\mathcal{V}\}$ whereas v_c denotes instantiations over only those random variables participating in the clique (c). The structure

Structural
Prior



Family
MSA



Graphical
Model

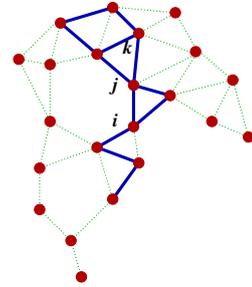


Figure 1: Residue coupling networks. (Top) A graph expressing a prior over possible coupling relationships. One source for a prior could be the contact graph representation of a protein’s three-dimensional structure; here, mechanistic explanations for coupling posit either a direct interaction between contacting residues, or an indirect (transitive) propagation of an interaction through networks of contacting residues. (Middle) The multiple sequence alignment for members of a protein family provides evidence for dependence and independence. In the example, positions i and k are very correlated—when i is a ‘filled in’ residue, k tends to be as well; similarly when i is ‘empty,’ k tends to agree. However, knowing j makes the positions rather independent. In the most common case where j is filled in, we see the combinations of types at i and k are more evenly distributed. This suggests that i and k are conditionally independent, given j . (Of course, even in this example, noise obscures the degree of independence.) (Bottom) A graphical model (darkened edges) captures conditional independence. We construct such a model by selecting edges from the prior that best decouple other relationships. For example, we see that the conditional independence of i and k given j can be explained by a transitive propagation of interaction along model edges.

of the potential functions satisfies:

$$\prod_{c \in \text{cliques}(N)} \phi_c(v_c) = \frac{\prod_c P(v_c)}{\prod_{a \in \text{cliqueadj}(N)} P(v_a)} \quad (3)$$

In other words, the likelihood is given by the product of marginals defined over the cliques of N divided by the product of marginals defined over the clique adjacencies of N (cliqueadj, which could be nodes, edges, or general sub-graphs). In this view, each potential of Eq. 1 is either a conditional or a joint marginal distribution. For instance, in an undirected network over three variables and two edges, with adjacencies (a, b) and (b, c) , the product of the potentials is given by:

$$\phi_{a,b}\phi_{b,c} = \frac{P(a, b) \times P(b, c)}{P(b)}$$

We can view $\phi_{a,b}$ to be the conditional $(\frac{P(a,b)}{P(b)})$ and $\phi_{b,c}$ to be the marginal $(P(b, c))$, or vice versa.

Two well-known theorems in the probabilistic models literature [17] reconcile the independence and factorization viewpoints. First, if a distribution factorizes according to Eq. 1, then it satisfies the *Global* interpretation (and hence, the *Local* and *Pairwise* interpretations as well). Second, the Hammersley-Clifford theorem [3] states that if a joint pdf is positive everywhere (i.e., it has non-zero mass for all arguments), then it factorizes according to Eq. 1 iff it satisfies the *Pairwise* property (notice the bidirectionality of this theorem). Combining the above two theorems, we have: if a jpdf is positive everywhere, then the above three properties—*Pairwise*, *Local*, and *Global*—are equivalent. Any one of them holding true will imply the others.

In what follows, we adopt a statistical estimator of joint probability that assigns non-zero probability mass to every possible sequence. Thus, since the positivity assumption is satisfied, we can adopt any of the above three interpretations to infer independence between residue positions. In this case, the *Local* interpretation is easiest to operationalize. The *Pairwise* interpretation requires us to ‘fix’ (condition on) all but one residue and it is unlikely that this will retain a significant enough portion of the MSA to be confident about any probability assessments. The *Global* interpretation does not suffer from this drawback but makes the independence assessment more complicated by relying on a graph separation test.

If our MSA were sufficiently large and diverse enough to represent the joint probability of the family, then it is clear that the best unbiased estimator would be the maximum likelihood estimator (i.e., simply take the frequencies from the MSA). As the clique size grows, however, it is unlikely that the MSA is sufficiently representative of every possible clique value (i.e., set of residue types for the nodes). Therefore, we must consider the possibility that a clique value may not occur in the MSA but still be a member of the family. To this end, we adopt the following estimator for the probability of a clique value

$$P(c) = \frac{f(c) + \frac{\alpha N}{20^{|c|}}}{N(1 + \alpha)} \quad (4)$$

Here $f(c)$ is the frequency of the clique value in the MSA, N

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function InferNetwork ( $G = (V, E)$ )
 $\mathcal{V} \leftarrow V$ ;  $\mathcal{E} \leftarrow \emptyset$ 
 $s \leftarrow \text{Score}(\mathcal{V}, \mathcal{E})$ 
 $C \leftarrow \{(e, s - \text{Score}(\mathcal{V}, \mathcal{E} \cup \{e\})) | e \in E\}$ 
repeat
   $e \leftarrow \arg \max_{e \in E - \mathcal{E}} C(e)$ 
   $\mathcal{E} \leftarrow \mathcal{E} \cup \{e\}$ 
  for all  $e' \in E - \mathcal{E}$  such that  $e$  and  $e'$  share a vertex
  do
     $C(e') \leftarrow C(e') - \text{Score}(\mathcal{V}, \mathcal{E} \cup \{e'\})$ 
  end for
until stopping criterion satisfied

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Figure 2: Algorithm for inferring a residue coupling network.

is the total number of sequences in the MSA, $|c|$ is the size of the clique and α is a parameter that weights the importance of missing data. Notice that even when a particular clique value does not appear in the MSA, it still has a positive (but small) probability. This satisfies the desired positivity constraint. We are actively developing more sophisticated estimators, but results show that Eq. 4 is effective in practice. We employ a value of .1 for α but tests (data not shown) indicate that results are similar for reasonable values of α (between .01 and .25).

Uncovering graphical models from datasets is known to be an NP-hard problem in the general case and researchers typically restrict either the topology of the network (e.g., to trees [14]) or adopt heuristics to search the space of possibilities. In this paper, we assume the existence of a candidate set of edges (a graph prior; see below) and propose heuristics that sequentially infer conditional *independences* among this set (rather than dependences as followed in prior work). If we know that residues i and k become independent given j , i.e., the conditional mutual information

$$MI(i, k|j) = H(i|j) - H(i|k, j)$$

is zero, then it is easy to see that the removal of j and its incident edges must separate i and k in the unknown network N . This assessment is made in the context of a prior graph $G = (V, E)$, where we assume $\mathcal{V} = V$ and $\mathcal{E} \subset E$. This approach is akin to the ‘sparse candidate’ algorithm [8] for learning (directed) Bayesian networks.

Fig. 1 presents an example of such an inference. In attempting to de-couple position i from k , we need only consider neighbors of i (e.g., j) according to the graph prior. We consider here two priors: the complete graph or a contact graph. The complete graph is clearly an uninformative prior, assuming that all possible interactions are equally likely. The contact graph places edges between all pairs of residues that are ‘close-enough’ (e.g., with some atoms within some distance threshold) in the three-dimensional structure of the protein. (Since structure is more conserved than sequence, we assume that all members of the family adopt essentially the same contact graph and select one from the PDB.) Physically speaking, this is a reasonable assumption in seeking to uncover direct energetic interactions and in distinguishing indirect ones propagated transitively (e.g., one residue ‘pushes’ another, which ‘pushes’ a third). We compare here

results from these two priors, but note that other priors are possible, e.g., a graph accounting for functional information, coupling via an intermediate (ligand binding), or longer-range electrostatic coupling.

The score for a network, following the *Local* interpretation, is given by:

$$\text{Score}(N(\mathcal{V}, \mathcal{E})) = \sum_{n \in \mathcal{V}} \sum_{m \notin \text{neighbors}(n)} MI(n, m | \text{neighbors}(n))$$

In de-coupling a pair of positions i and k given neighbor j , rather than aiming for absolute independence ($MI(i, k | j) = 0$), we assess by how much the conditional mutual information is decreased. We use the notion of network score to define an edge score as the difference in score between the network without the edge and the network with the edge. Note that the score of an edge can be negative, if adding the edge produces more coupling in the network. Given the ability to evaluate the edges, we greedily grow a network by, at each step, selecting the edge that scores best with respect to the current network. Fig. 2 gives this algorithm. The algorithm can be configured to utilize various greedy stopping criteria—stop when the newly added edge’s contribution is not significant enough, stop when a designated number of edges have been added, or stop when the likelihood of the model is within acceptable bounds.

The run-time of our algorithm depends on n , the number of residues in the protein of interest and d , the maximum degree of nodes in the prior. With an uninformative prior, d is n . For stronger priors (e.g., a contact graph), we can assume a bounded number of neighbors for any residue, so d is $O(1)$. The algorithm scores $O(dn)$ edges at each iteration. Naive execution of the algorithm requires that the score of the network be computed for each edge at each iteration. Scoring a network requires $O(n)$ MI computations for each residue and there are n residues, so naive execution requires $O(dn^2)$ MI computations at each iteration. Since conditioning contexts change dynamically during the operation of the algorithm, we cannot perform any *a priori* pre-processing to accumulate sufficient statistics (in contrast to global methods where mutual information between all pairs of residues can be computed in a single pass). However, the cost of making fresh assessments is curtailed since conditioning contexts are merely subsets of neighbors. Thus by caching values efficiently we can improve the runtime by a factor of $O(n^2)$ at each iteration. First, precompute the score of every edge in consideration, requiring $O(dn^2)$ MI computations. At each iteration, rather than recomputing scores, pick the edge in the cache that improves the score of the network the most. This requires $O(n)$ time, but does not require any MI computations. The key observation is that after an edge is added, the only edges whose scores change are those incident to the edge just added. Since there are at most $O(d)$ of those that need to be updated, we need only $O(dn)$ MI computations, for a speedup of $O(n^2)$. Additional constant factor speedups can be achieved by removing at each step edges that produce statistically unsound conditioning contexts.

4. EXPERIMENTS

We illustrate our algorithm for inferring residue coupling networks with two protein families: GPCRs (G-protein cou-

pled receptors) and PDZ domains. GPCRs are membrane-bound proteins critical in intracellular communication and signaling, and a key target of molecular modeling in drug discovery. Since ligand binding at the extracellular face initiates propagation of structural changes through the transmembrane helices and ultimately to the cytoplasmic domains, GPCRs make an appropriate and compelling study for network identification [26]. PDZ domains are protein-protein interaction domains that occur in many proteins and are involved in a wide variety of biological processes [10]. One role of PDZ domains is assisting in the formation of protein complexes by binding to the C-termini of certain ligands [10]. Through these two studies we aim to explore many pertinent aspects of our approach, such as how to set priors, studying the progress of the algorithm as new edges are added, using the induced graphical model for classifying protein sequences, and biological interpretation of the results.

4.1 Results

4.1.1 GPCRs

In the GPCR study, we evaluate the use of protein contact graphs as priors and also explicitly relate the structure of our identified networks with those previously identified [26]. We first retrieved the multiple sequence alignment of 940 members of the class A GPCR family, each with 348 residues, as discussed in [26]. In order to explore contact graph priors, we constructed a contact graph from the three-dimensional structure of one prominent GPCR member, bovine rhodopsin (PDB id 1HZX), identifying 3161 pairs of residues with atoms within 7 Å. We verified that the residues previously identified as belonging to networks [26] form connected sub-graphs of this contact graph.

For this study, in testing conditional mutual information, we only considered cases for which at least 15% of the original set of sequences remained after subsetting to a particular residue type. That is, we only allowed a residue to pick neighbors that, when restricted to their most common amino acid type, retain at least 15% of the original sequences. As discussed [18], such a bound is required in order to ensure sufficient fidelity to the original MSA and allow for evolutionary exploration. Our bound of 15% is roughly half that used in [26], since our algorithm subsets according to multiple residues, depending on the number of neighbors available, whereas the previous algorithm subsets according to only one residue. From extensive experiments with this parameter (data not shown), we found that while there is some variation in the edges with changes of this parameter, many (> 70%) of the best edges are insensitive to the exact threshold.

In order to evaluate the implications of restricting dependencies to structural neighbors, we compared the MI scores for edges in the protein contact map against those for all pairs of residues. This tested the hypothesis that the bulk of the correlation could be explained as correlation between structural (contact graph) neighbors. For every residue, we identified both the best decoupler *anywhere* in the protein, and the best decoupling contact graph neighbor. Fig. 3 shows the absolute differences between these values. Notice that in most cases, the best neighbor provides nearly as much decoupling as the best residue elsewhere in the graph.

However, there are some nodes that incur a large penalty. In general, these nodes are highly conserved and therefore have small scores against all other nodes. However, since the total number of residues is large, the sum of all these small correlations becomes non-trivial. When a node is sub-setted, making an originally highly conserved node become perfectly conserved, the score for that node drops to 0. In this case there is a large difference in improvement between selecting a distant node and a node from the original prior graph. It is important to keep these caveats in mind in the discussion that follows.

Our first model inference test was to start with the previously identified network of Suel *et al.* [26], use its induced subgraph of the contact graph as input to our algorithm, and see if we could recover the network. There are 144 edges to be considered. The algorithm constructed a model with 52 edges, after which point no other edge could be added without making the score worse, so the algorithm terminated. Fig. 5 (left) illustrates the 52-edge network identified by our algorithm. Fig. 4 (red) shows the change in score as edges are added to the network. Notice the score decreases as edges are added and levels out toward the end (leading to termination when any remaining edge would increase the score).

To study the influence of the contact graph prior, we re-ran our algorithm using an uninformative prior so that all pairs of residues would be tested for inclusion. This time, the algorithm considered 1080 edges and picked 67 of them for inclusion before terminating with no edges available to improve the score. The resulting network has a better score than that of the network under the contact graph prior (Fig. 4 (blue)), but does not have as nice a visualization (Fig. 5 (right)).

Since the score differences between these two runs were substantial, we investigated the best possible score achievable for this protein family. Towards this end, we randomly shuffled the columns of the MSA, yielding a new MSA having the same level of conservation for each residue but with correlation lost due to the independent shuffling. We measured the correlation in 2500 of these MSAs (which consisted of just noise) by computing the score of the empty network (one with no edges) on the MSA. The resulting scores were normally distributed over a small range (63.5 to 65.1) with mean value 64.3. This means that for the GPCR family, if we accounted for all possible correlation we would expect a score of about 64.3. The algorithm run with the uninformative prior scores 73.6, well within the margin of error we would expect due to the greedy property of our algorithm or the nature of the conditioning contexts.

While our modeling formulation is different in nature from that of Suel *et al.* (independence vs. dependence, small number of parameters, etc.), our model that used the uninformative prior identifies many of the same biologically relevant features. For example, Suel *et al.* identify coupling between residues 296 and 265 that form “part of a linked network extending parallel to the plasma membrane from 296 to form the bottom of the ligand-binding pocket.” Our algorithm likewise identifies an edge between residues 296 and 265. Several other identified interactions appear as *indirect* re-

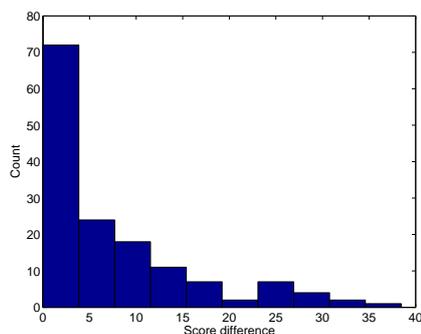


Figure 3: Penalty for decoupling using a contact graph neighbor rather than any residue (frequency distribution). Lower score differences indicate that neighbors perform as well as other residues.

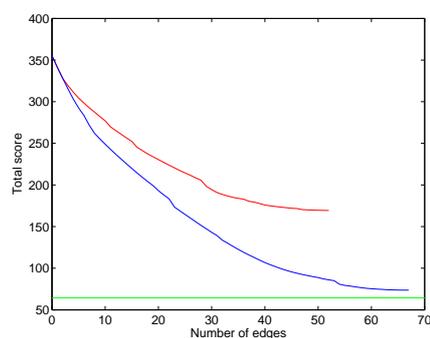


Figure 4: Improvement of MI score as edges are successively added for the contact graph prior (red) and uninformative prior (blue). The green line shows a lower bound for the score for the GPCR MSA.

lationships in our model. For example, coupling between residue 296 and 293, identified as a “helical packing interaction” is identified by our model as being indirect. In this case, residue 117 actually makes residues 296 and 293 conditionally independent, lowering their mutual information scores from .3347 to .0259. This is true also of the coupling between residue 296 and residues 298 and 299. These couplings are part of “a sparse but contiguous network of inter-helical interactions linking the ligand-binding pocket with the cytoplasmic surface.” Both 296/298 and 296/299 become conditionally independent in the presence of residue 117.

Although our algorithm does produce many of the relationships as identified by Suel *et al.*, there are several differences between the models. For instance, our network does not identify the coupling between residues 296 and 113 which “makes a salt-bridge interaction with the protonated form of the Schiff base,” as either direct or indirect. Nor does our algorithm find the “inter-helical packing interaction” between residues 296 and 91. Conversely, our algorithm finds a strong direct coupling between residues 296 and 117 as well as between residues 90 and 91. Further investigation into

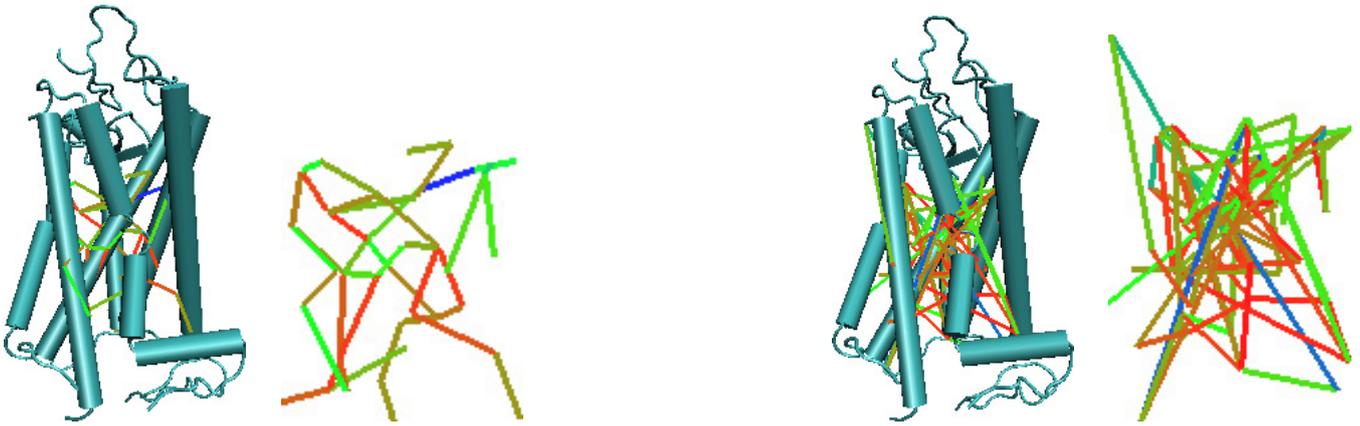


Figure 5: GPCR network identification: three-dimensional structure of bovine rhodopsin with overlaid network, and just the network for model inferred from (left) contact graph induced by the previously published network and (right) uninformative prior comprising all pairs of edges. Edges are colored by score, with red the strongest ‘decouplers’ and blue the weakest.

these strong couplings may be of interest to biologists (e.g., by mutagenesis studies). This illustrates the ability of our approach to help formulate testable biological hypotheses.

4.1.2 PDZs

In the PDZ study, we demonstrate the utility in subsequent analyses of the graphical models learned by our algorithm. We study the ability of our inferred residue coupling networks to capture the ‘essence’ of a protein, namely in classifying PDZ domains. Traditionally, PDZ domains have been classified into two types according to which type of ligand they bind. The first class of PDZ domains binds to C termini with sequences S/T-X- Φ (Φ is a hydrophobic residue) while the second class targets sequences of the form Φ -X- Φ . Although the two classes in this protein family may be defined by simple sequence motifs, we show that coupling-based models provide more discriminatory power, and we use this opportunity to subject our approach to a rigorous evaluation in a maximum likelihood framework.

We obtained MSAs for the two classes of PDZ domains from PDZBase [2] by querying according to the ligand type and removing duplicate entries, thereby obtaining 95 class I and 12 class II sequences. We ran our algorithm on the sequences in class I using an uninformative prior (no contact graph). After adding 85 of a possible 5671 edges to our model, the *MI* score converged (as was previously demonstrated with the GPCR family).

Using the estimator of Eq. 4, we compared the likelihoods from proteins in class I and II against different models, in a leave-one-out cross-validation test. Fig. 6 (top) shows the evolution of likelihood scores as edges are added to our model. On the far left of the plot is the likelihood based solely on conservation (i.e., with no edges in the network). As the network grows, so does its power to discriminate classes. Thus we conclude that conservation alone does not adequately represent the multiple sequence alignment. Once 40 edges are added to the network, the model has the power to discriminate perfectly between the two classes. We could

continue to the limit by adding all edges to the network. In this case, we would derive a clique, with a joint distribution over all residues that would provide a reasonable score *only* for sequences in the original alignment. The convergence of the *MI* score prevents our algorithm from overfitting in this manner.

Fig. 6 (bottom) shows a receiver operating characteristic (ROC) curve that illustrates the classifying power of the conservation-based model and our inferred residue coupling network. The figure shows that classification of proteins can indeed be improved by moving beyond models that consider conservation alone to models that properly account for coupling relationships.

4.2 Comparison with Other Approaches

There are multiple dimensions along which our approach can be compared to others. The graphical models uncovered by our algorithm lie between a purely conservation-based representation of a protein family, and a dense representation of all co-variation within that family. As our results show quantitatively, we are able to account for the bulk of the co-variation with a significantly smaller number of parameters than is required by the complete graph assumed by other coupling studies. Thus our models should not overfit, but still account for significant coupling missed by pure conservation. Perhaps more importantly, while we employ the same co-variation analysis at the heart of our algorithm, none of the prior works results in a probabilistic model of any form, and hence none of them can systematically decompose observed co-variation into a core set of functional dependences, as is done here. This shortcoming holds even for the pioneering work on perturbation analysis [18, 26], since the ‘networks’ mined cannot be directly used as predictive models (e.g., from which new sequences belonging to the family can be drawn) or even as statistical indicators of variation (e.g., for assessing the likelihood of additional sequences). The approach presented here clearly overcomes these drawbacks by providing models that encode probabilistic assumptions of data and which can be genuinely fal-

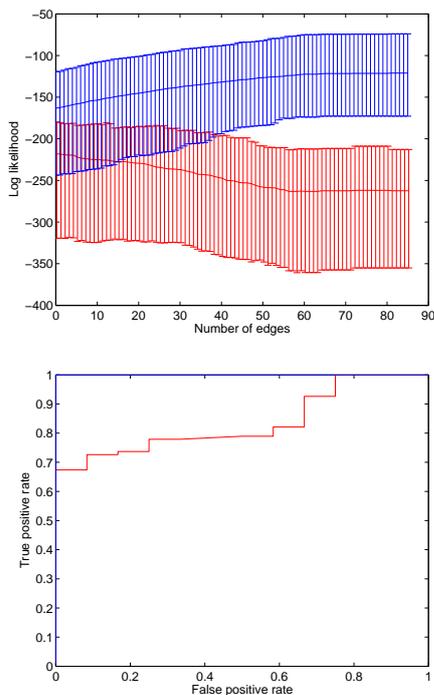


Figure 6: Evolution of likelihood as edges are added to the network. (Top) Sequences from class I (blue) and class II (red) against the class I model. Each plot shows the mean, maximum and minimum likelihood. The far left of the plot is the model based only on conservation. As the number of edges grows, more correlation is captured by the model. The far right is the model that contains all the correlations found by our algorithm. (Bottom) ROC curve showing the power of classifying by likelihood using only conservation (red) or the converged model produced by our algorithm (blue, following the box boundary).

sified given appropriate data. We anticipate that this work will serve as a catalyst for more model-driven research into coupling networks.

5. DISCUSSION

This work marries research into residue co-variation with probabilistic graphical models, producing a systematic and sound algorithmic approach to inferring residue coupling networks underlying protein families. Our use of conditional mutual information as a criterion for growing a network means that our algorithm can also be viewed as a perturbation-based approach; however, in contrast to [26] who infer coupling between the perturbed position and another position, we infer independence between residues on either side of the perturbed position. The results indicate that independence of residues can be a good guiding principle for the discovery of evolutionarily conserved structure.

While there are other ways to infer networks from covariation data (e.g., gaussian graphical models [5]) they either

require the specification of complete sets (e.g., all pairs) of dependency information or must necessarily make assumptions about the parametric form of interrelationships. In contrast, our approach employs the broader notion of independences to situate the network. In addition, it models *all* significant couplings and conditional independences, hence capturing the essence of what it means to belong to a given family. This has tremendous applications in protein fold classification and protein design.

An important feature of our approach is the ability to make (selective) use of prior information towards a coupling study. Some priors (e.g., the contact graph) aid interpretability of the results but (as shown in our tests) might not yield as good as a model. There may be other potential explanations for observed couplings (e.g., electrostatics, ligand binding) that could be incorporated in the prior. Conversely, in the course of the algorithm, edges could be scored not only for reduction in *MI* but for consistency with a background theory.

The success of the approach is dependent on the quality of the provided MSA. We would like to scale up our algorithms to work with MSAs involving greater numbers of sequences, and thus more complete samplings of families. Inferring graphical models from such large datasets will benefit from research aimed at scaling up model inference (e.g., see [12]) and we propose to consider these for inferring coupled residues. We would also like to ensure fidelity of the alignment, particularly by using available structural information. Eventually, we hope to integrate alignment and model inference, perhaps employing shared hidden variables so that they iteratively improve each other.

Since motifs can be viewed as a limiting case (conservation only) of coupling relationships, we intend to build upon the work in that domain on representing general traits. For instance, we intend to relax our modeling of residues as distributions over amino acids, and instead consider distributions over *classes* of amino acids (e.g., polar, hydrophobic, small). Since there are multiple, overlapping, taxonomies of amino acids [27] we can even assume a hidden variable model (denoting an unknown relabeling of each residue) and attempt to infer the network as well as the relabeling function from a given MSA and contact map. An alternative is to employ a scoring matrix in evaluating extent of co-variation [24].

Finally, we intend to explore applications in protein design. Sampling from an inferred model is a natural way to generate new representatives of a family. Simultaneous construction of models for multiple families could help define their boundaries and thus even enable control over specificity in design.

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