

# *Garcia Robots, An Introduction*

CS 23



# ***Hardware Architecture***



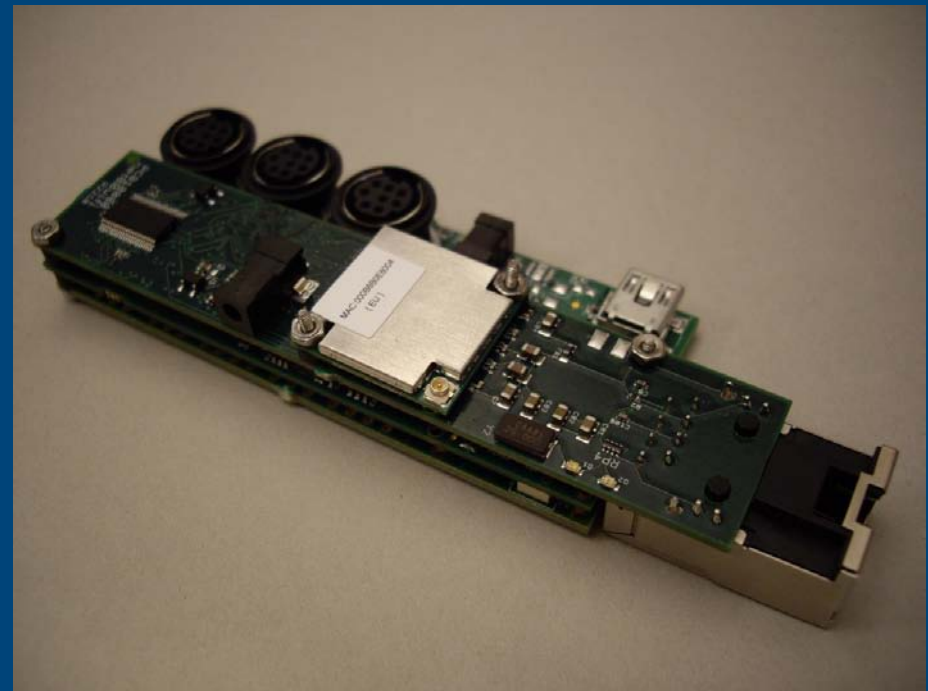
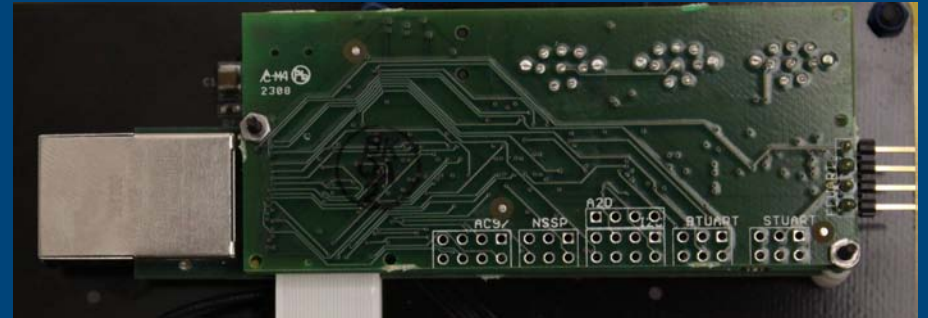
# *HW Architecture*

- The Gumstix Board
  - Embedded Linux
- The Brainstem Board
  - On-board sensors
  - On-board motors.
- The Wireless Sensor
- The Webcam



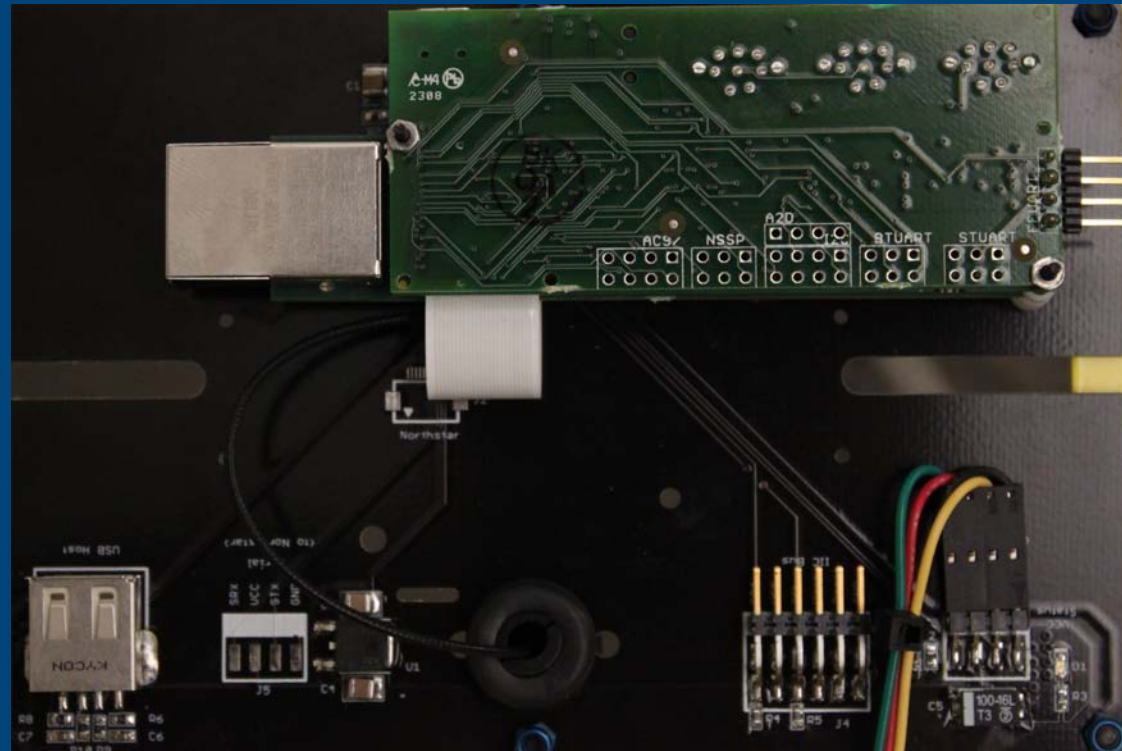
# HW Architecture

- Gumstix Verdex Pro
  - A Marvell 600MHz PXA270 Intel Processor flashed with a Linux OS.
  - On board flash disk and memory.
  - Multiple serial ports, one USB 1.1 port, an Ethernet port , a wifi 802.11 card.



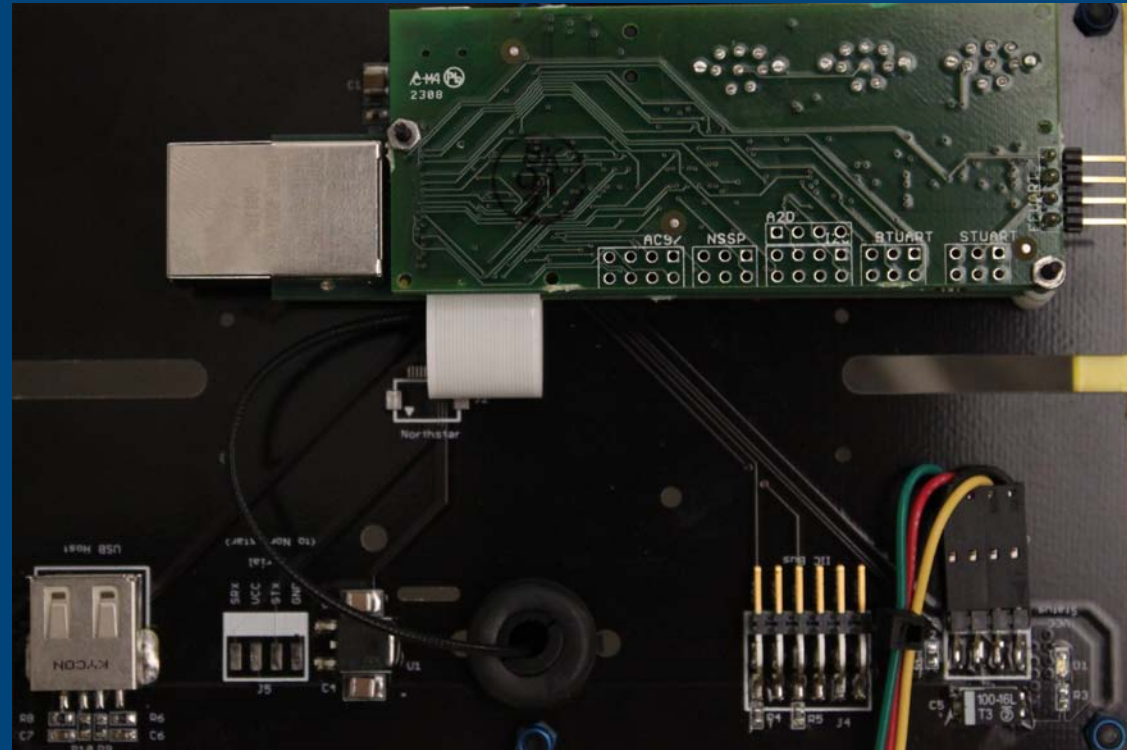
# Gumstix Cont.....

- Two serial ports:
  - Upper right is used as the default text terminal.
  - Lower right is used to connect to Brainstem.



## *Gumstix Cont...*

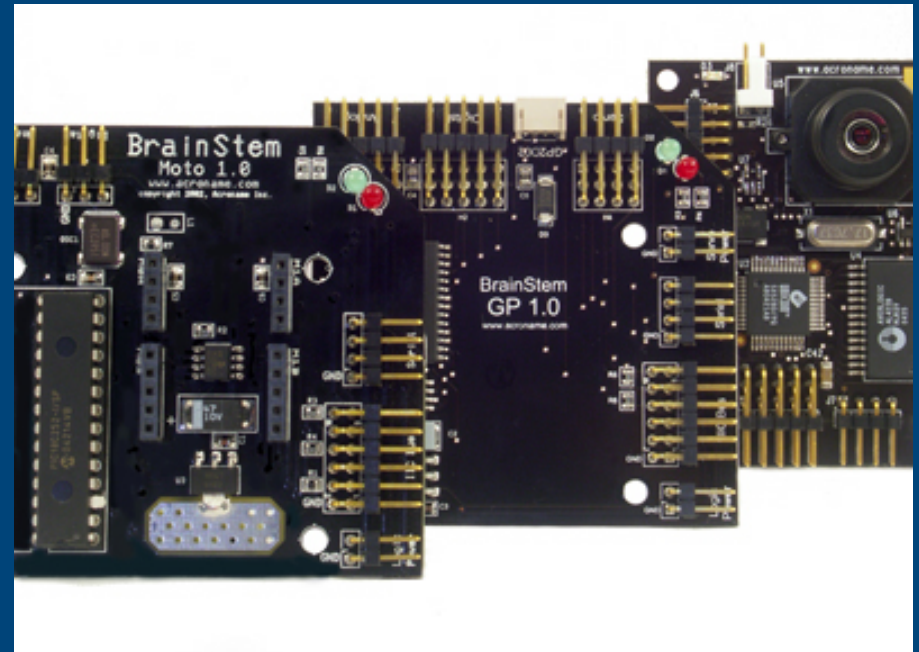
- USB is connected to a USB-hub, which is connected to a web cam and a wireless sensor (tMote)



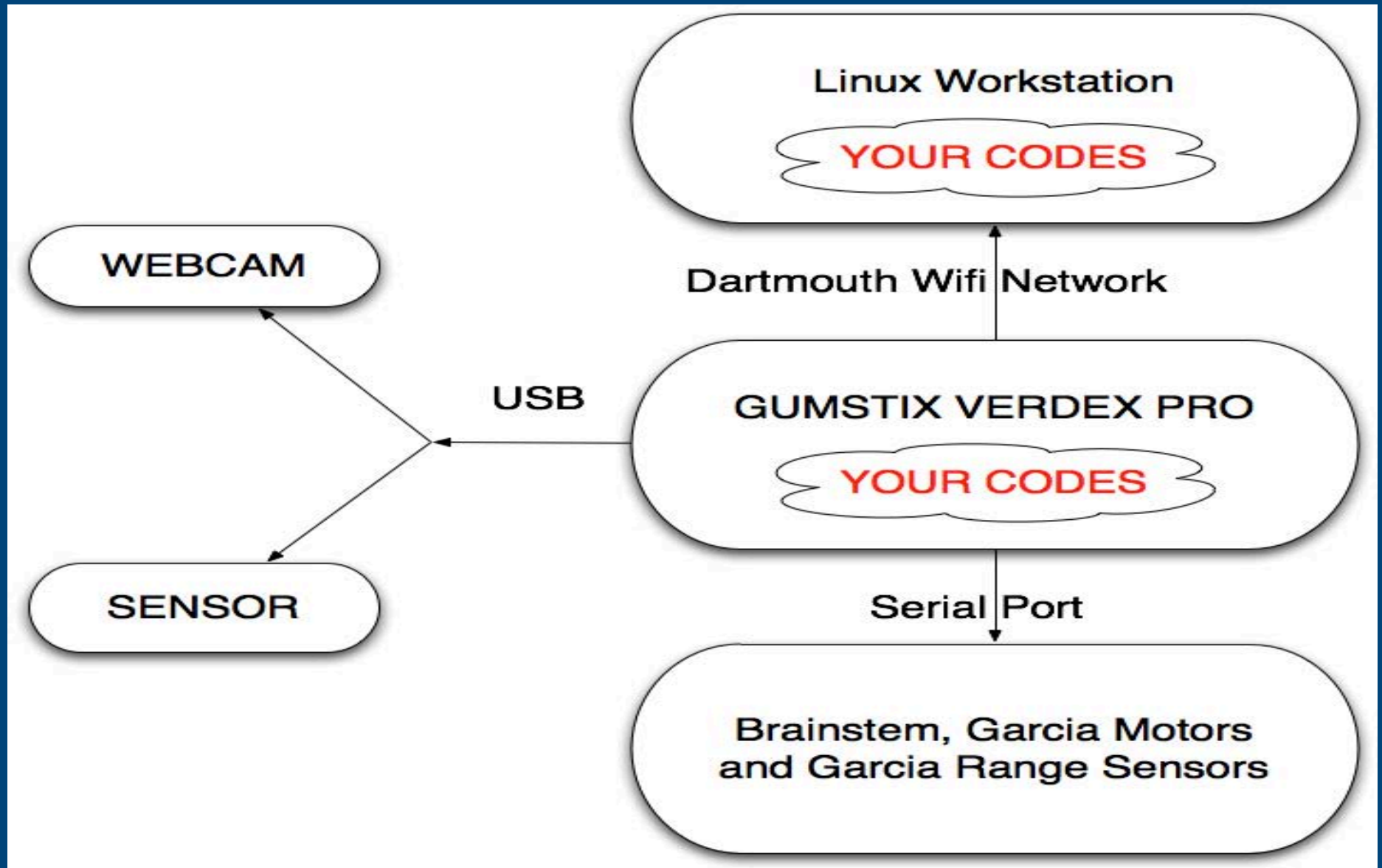


# *Brainstem (by Acroname)*

- A special circuit board to receive commands from the serial port and execute them.
- Motors and range sensors are connected to Brainstem.



# HW Architecture Overall





# ***Embedded Linux***



# *Gumstix Embedded Linux*

- A 2.6.21 patched linux kernel.
- Full support for many devices (webcam, sensors,...)
- JSFF2 file-system, accessing files on Flash chips as on hard drives.

# Demo 1: Log on to Gumstix

- Connect robots to the computer with a RS232 cable.
  - Type “minicom” in the computer
  - Start the robot!
  - User: root
  - Password: gumstix
  - *Be careful, because you have the power to delete things you shouldn't!*
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## *Demo 2: Using Dartmouth Wireless*

- Your robot is running under the “Dartmouth Registered” network with a fixed IP address 129.170.210.x.
  - Actual IP addresses listed on project page
- Let's ssh to the robot and play with the linux for a while.

# *Demo 3: Hello World Cross-Compiling*

- Write a helloworld.c
- Compile it with cross-compiler at:
  - [fedora]\$/usr/local/gumstix/gumstix-oe/tmp/cross/bin/arm-angstrom-linux-gnueabi-gcc -o helloworld helloworld.c
- Now try type:
  - [fedora]\$file helloworld
  - helloworld: ELF 32-bit LSB executable, ARM, version 1 (SYSV), dynamically linked (uses shared libs), for GNU/Linux 2.6.14, not stripped

# *Demo 3:*

## *Copying helloworld to Gumstix and run*

- We need scp (copy via ssh).
  - [fedora]\$scp ./helloworld root@[the gumstix ip]:~/