

CS31 (Algorithms), Spring 2020 : Lecture 15

Date:

Topic: Graph Algorithms 5: Maximum Flow equals Minimum Cut; The Ford-Fulkerson Algorithm

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In the last lecture we showed that the maximum s, t flow is *at most* the minimum s, t cut. Furthermore we looked at the conditions which would prove max-flow equals min-cut. Let's recall that theorem for we will use this later.

Theorem 1. Suppose f is a feasible s, t flow f , and S is an s, t cut S such that

1. $f(e) = u(e)$ for all $e \in \partial^+ S$
2. $f(e) = 0$ for all $e \in \partial^- S$

Then f is a **maximum** s, t flow, S is a **minimum** s, t cut, and their values are the same.

In this lecture, we will prove the **strong duality** theorem: in any network, the maximum value of an s, t flow equals the capacity of the minimum s, t cut. We do so via an *algorithm*. That is, we describe an algorithm which in one swoop solves both the MAX- s, t -FLOW and the MIN- s, t -CUT problem, and also proves their respective values are the same. This algorithm was designed by Lester Ford and Dilbert Ray Fulkerson in the 1950s, and is called the Ford-Fulkerson algorithm. To describe this, we first introduce the concept of the *residual networks*.

1 The Residual Network

Let us start with an algorithm for finding maximum flows that *doesn't* work. Recall what we need to do: we need to find a valid flow $f : E \rightarrow \mathbb{R}_{\geq 0}$ such that $\text{excess}_f(t)$ is maximized. We start with the zero flow: $f(e) = 0$ for all $e \in E$, and try to *increase* this flow in iterations. Now consider an s, t -path p in the graph G . Given such a path p , we can *augment* the current flow f *along the path* p as follows:

- Let $\delta = \min_{e \in p} u(e)$
- For every $e \in p$, set $f(e) \leftarrow f(e) + \delta$.

Note that flow conservation remains valid; the total in-flow at any $v \neq s, t$ is equal to the total out-flow – it is either δ or 0. Also note that by choice of δ and since we started from the 0-flow, the capacity constraint also remains valid. Finally, the $\text{excess}_f(t)$ increases by δ . Progress!

How should we proceed? We could repeat the steps above, namely, find another s, t -path p and then augment flow along path p . However, we have already sent some flow which could have used up some capacity of certain edges e . In the augmentation step we should be wary of this lest we violate the capacity constraint. The fix is to maintain a **residual capacity** $u_f(e)$ for every edge e . These are initially set to $u(e)$, the original capacity, but for every unit of flow that we pass through this edge, we must *decrease* its residual capacity. This leads to the following augmentation procedure along path p *given* we have sent flow f :

- Let $\delta = \min_{e \in p} u_f(e)$
- For every $e \in p$, set $f(e) \leftarrow f(e) + \delta$.

- For every $e \in p$, set $u_f(e) \leftarrow u_f(e) - \delta$.

The above process can be repeated over and over again, and every time the value of the flow increases by δ . We stop when $\delta = 0$, that is, we can't find any path p from s to t with $\min_{e \in p} u_f(e) > 0$. How would we check this? Simple: remove all edges with $u_f(e) = 0$ and check if there is a path from s to t . We write the full algorithm below.

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1: procedure NAIVEMAXFLOW( $G, s, t, u$ ):
2:   Start with  $f \equiv 0$  and  $u_f(e) = u(e)$  for all  $e$ .
3:   ▷ Invariant:  $u_f(e) + f(e) = u(e)$  for all  $e$ .
4:   while true do:
5:     Find any path  $p$  from  $s$  to  $t$  with  $\min_{e \in p} u_f(e) =: \delta > 0$ .
6:     If no such path break
7:     For every edge  $e \in p$ :  $f(e) \leftarrow f(e) + \delta$ ;  $u_f(e) \leftarrow u_f(e) - \delta$ .
8:   return  $f$ 

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As can be guessed by the name and the color of the shading, the algorithm above, although a solid try, doesn't return the correct solution. Let's see an example where it fails (maybe you'd like to try to find one first before peeking?): see [Figure 1](#).

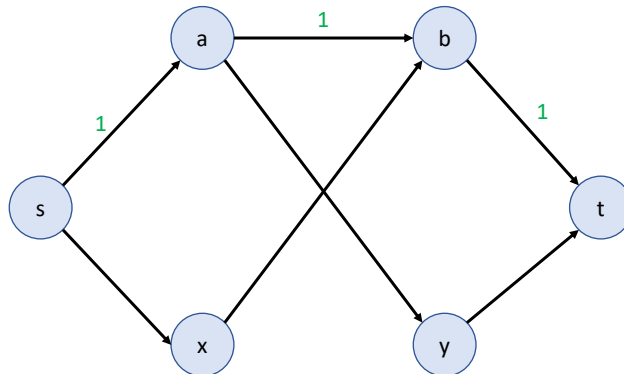


Figure 1: In this graph G , all edges have unit capacity. If we send our first augmentation along the path $p = (s, a, b, t)$, then we would send 1 unit of flow on this. All these edges would have $u_f(e) = 0$ and deleting these edges disconnects s and t . Thus the NAIVEMF algorithm would terminate. On the other hand, there is a flow of value 2 which sets $f(e) = 1$ for all edges except (a, b) . This would have been achieved if we sent flow first on the path (s, x, b, t) and then (s, a, y, t) . But how would we know to do that?

In a sense, the flow we chose to send, that is the one on the path (s, a, b, t) was a *mistake*. The main idea behind the notion of the residual network is to keep safeguards which help us correct mistakes when made. This is a general life principle, but something which beautifully works in the case of s, t flows.

Definition 1. Given a flow network (G, s, t, u) and a valid flow $f : E \rightarrow \mathbb{R}_{\geq 0}$, the *residual network* with respect to flow f denoted as G_f is defined as follows:

- $G_f = (V, E_f)$ where $E_f = E \cup E_{rev}$

- $E_{\text{rev}} = \{(v, u) : f(u, v) > 0\}$, that is, E_{rev} contains the *reverse* of all edges which carry positive flow.
- The residual capacity on edges in E_f is defined as follows

$$u_f(x, y) = \begin{cases} u(x, y) - f(x, y) & \text{if } (x, y) \in E \\ f(y, x) & \text{if } (x, y) \in E_{\text{rev}} \end{cases}$$

Let us draw the reverse graph for the network in Figure 1 with respect to the flow of unit 1 sent along the path s, a, b, t . This is shown in Figure 2.

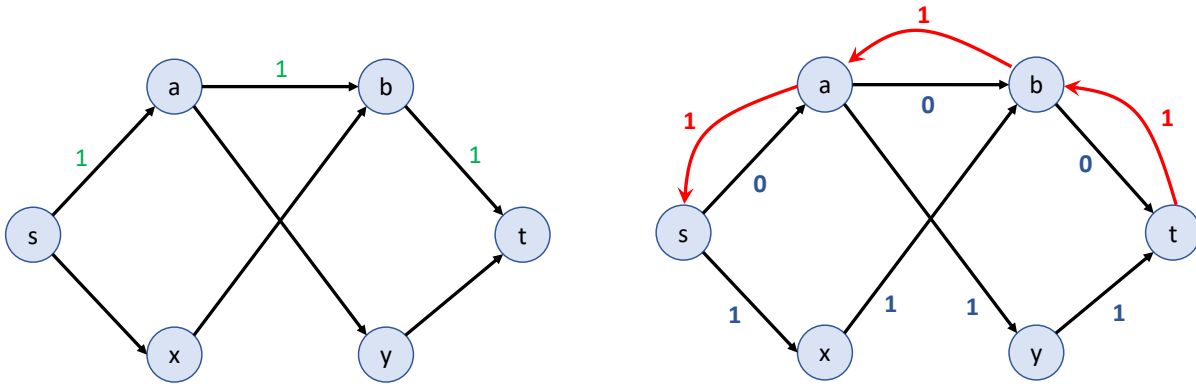


Figure 2: The graph in the left shows the flow in green. The graph in the right is the residual graph. The red edges are E_{rev} . The numbers are the residual capacities.

Why is the residual network important? Well, note that after the flow f is sent on the path (s, a, b, t) , the residual network G_f *does* have a path from s to t where every edge has a residual capacity $u_f(e) > 0$; this path is $q = (s, p, b, a, q, t)$. As you can see, this path contains one edge (b, a) which is not in E but in E_{rev} .

The question that should come into your mind now is: so what? The edge (b, a) doesn't even exist in the graph G ; why are we bothering with such abstract constructs? Well, suppose you suppressed those thoughts and tried to *augment* flow along this path q . (Wait! Firstly there is no edge (b, a) and now you are asking me to send flow across it?) But here's the point: we know that since $(b, a) \in E_{\text{rev}}$ there must exist $(a, b) \in E$ with $f(a, b) > 0$. Indeed, $f(a, b) = u_f(b, a)$. So *increasing* flow along the dummy reverse edge $(b, a) \in E_{\text{rev}}$ is actually just a short-hand for *decreasing* the flow along the edge (a, b) . This augmentation is indicating that our first choice of sending flow across the edge (a, b) was perhaps a "mistake", and this is fixing it. Indeed, this is the conceptual abstraction of the residual network: send flow along edges, but keep the reverse edges as stop guards to rectify potential mistakes. Now we are ready to formally give the algorithm.

2 The Ford Fulkerson Algorithm

First, we formally define what augmentation along a path in a residual network means.

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1: procedure AUGMENT( $G_f, s, t, p$ ):
2:    $\triangleright$  Augment along path  $p$  in the residual network  $G_f$ .
3:    $\triangleright$  Modifies  $f(e)$  for every  $e \in G$ ; modifies  $u_f(e)$  for every edge  $e \in E_f$ .
4:    $\delta := \min_{e \in p} u_f(e)$ .
5:   For every edge  $e = (x, y) \in p$ :
     • If  $(x, y) \in E$ :
       -  $f(x, y) \leftarrow f(x, y) + \delta$ ;
       -  $u_f(x, y) \leftarrow u_f(x, y) - \delta$ ;
       -  $u_f(y, x) \leftarrow u_f(y, x) + \delta$ ;
     • If  $(x, y) \in E_{\text{rev}}$ :
       -  $f(y, x) \leftarrow f(y, x) - \delta$ ;  $\triangleright$  Note:  $(y, x) \in E$ 
       -  $u_f(y, x) \leftarrow u_f(y, x) + \delta$ ;
       -  $u_f(x, y) \leftarrow u_f(x, y) - \delta$ ;

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The following invariants should be checked from the pseudocode above.

Claim 1 (Invariants of Augmentation).

- I1. For every edge $e \in E \cup E_{\text{rev}}$, $u_f(e) \geq 0$
- I2. For every edge $(x, y) \in E$, $f(x, y) + u_f(x, y) = u(x, y)$
- I3. For every $(x, y) \in E_{\text{rev}}$, $f(y, x) = u_f(x, y)$.

Claim 2. If f satisfied the capacity constraints before AUGMENT, then it does so after AUGMENT too.

Proof. This follows from the Invariants: For any edge $(x, y) \in E$, we have $f(x, y) = u(x, y) - u_f(x, y) \leq u(x, y)$ (from I2 and I1, respectively). Similarly, I1 implies $u_f(y, x) \geq 0$, that is, $f(x, y) \geq 0$. \square

Claim 3. If f is an s, t flow in G which satisfies flow conservation constraints at every vertex $v \neq s, t$, then the flow after AUGMENT step also satisfies flow conservation constraints at every vertex $v \neq s, t$. Furthermore, $\text{excess}_f(t)$ goes up by δ .

Proof. If $v \notin p$, then there is nothing to discuss. So assume $v \in p$. Since $v \notin \{s, t\}$ it is an internal node in p and let (w, v) and (v, x) be the two edges of p incident on it. There are four cases to consider.

- Case 1: $(w, v) \in E, (v, x) \in E$. In this case, both $f(w, v)$ and $f(v, x)$ go up by δ , implying the increase in excess is 0.
- Case 2: $(w, v) \in E, (v, x) \in E_{\text{rev}}$. In this case, $f(w, v)$ goes up by δ and $f(v, x)$ goes down by δ , implying the increase in excess is 0.
- Case 3: $(w, v) \in E_{\text{rev}}, (v, x) \in E$. In this case, $f(v, w)$ goes down by δ and $f(v, x)$ goes up by δ , implying the increase in excess is 0.
- Case 4: $(w, v) \in E_{\text{rev}}, (v, x) \in E_{\text{rev}}$. In this case, both $f(v, w)$ and $f(v, x)$ go down by δ , implying the increase in excess is 0.

Let $(v, t) \in p$ be the edge incident on t . If $(v, t) \in E$, then $f(v, t)$ increases by δ and the flow on no other edge incident on t changes, implying $\text{excess}_f(t)$ goes by δ . If $(v, t) \in E_{\text{rev}}$, then $f(t, v)$ decreases by δ and the flow on no other edge incident on t changes, implying $\text{excess}_f(t)$ goes by δ . \square

Now we are ready to describe the maximum flow algorithm.

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1: procedure FORDFULKERSON( $G, s, t, u$ ):
2:   Initialize  $f \equiv 0$  and  $u_f \equiv u$  and  $G_f \equiv G$ .
3:   while true do:
4:     Check if there is an  $s, t$  path  $p$  in  $G_f$  with all  $u_f(e) = 0$  edges removed.
5:     If not, break.
6:     Else, AUGMENT( $G_f, s, t, p$ ).
7:   return ( $f, G_f$ ).

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Lemma 1. If $u(e)$ s are integer valued, then FORDFULKERSON returns an integer valued valid f in $O(nmU)$ time, where $U := \max_{e \in E} u(e)$.

Proof. Since the 0-flow is valid, and the Augmentation Claims imply AUGMENT maintains validity, we get that the final flow is valid. We claim that the Line 4 in AUGMENT will set δ to a positive integer valued. To see this, we need to prove u_f is integer valued. But this is true in the beginning (when $u_f \equiv u$), and since subsequently f is augmented in δ -installments, the f is always integral which in turn leads to u_f being integral. Furthermore, each time $\text{excess}_f(t)$ grows by $\delta \geq 1$. Since the final flow is valid, the total value of this flow $\text{excess}_f(t) \leq nU$ since there can be at most n edges of the form (v, t) and each has capacity at most U . Thus, the algorithm terminates in $O(nU)$ rounds. Finally, note each round takes $O(n + m)$ time. \square

The next lemma proves the flow returned is a max-flow by showing that the conditions of [Theorem 1](#) holds.

Lemma 2. The flow f returned by FORDFULKERSON when it terminates is a maximum valued flow.

Proof. We describe a cut induced by a subset S which satisfied the properties of the corollary. In fact, define

$$S = \{v : v \text{ is reachable from } s \text{ in } G_f \text{ with all } u_f(e) = 0 \text{ edges removed.}\}$$

Clearly, $s \in S$. Since the algorithm terminates, $t \notin S$.

Now fix an $(x, y) \in \partial^+(S)$. Since y is not reachable from s using positive residual capacity edges, we get $u_f(x, y) = 0$. By I2, this implies

$$\text{For } (x, y) \in \partial^+(S), \quad f(x, y) = u(x, y)$$

Now consider an $(x, y) \in \partial^-(S)$. Since x is not reachable from s using positive residual capacity edges, we get $u_f(y, x) = 0$ for $(y, x) \in E_{\text{rev}}$. That is,

$$\text{For } (x, y) \in \partial^-(S), \quad f(x, y) = 0$$

But these are precisely the conditions of [Theorem 1](#). Thus, f is a maximum s, t flow and S is a minimum s, t cut. In one swoop, FORDFULKERSON (+ one DFS) finds not only the max-flow but also the min-cut. \square

Theorem 2. Given a flow network (G, s, t, u) where $u(e)$ is a positive integer for every edge $e \in E(G)$, the FORDFULKERSON algorithm finds a maximum s, t flow which is integral, and a minimum s, t cut in $O(nmU)$ time, and $\max s, t$ flow equals $\min s, t$ cut.